

A geometry of 7-point planes

(Material Based on [Tay09, Chapter 6, pp 43-45])

(Wednesday 16th March 2014)

Abstract

The classification of finite simple groups gives four families of groups whose union is precisely the set of all finite simple groups. However, when are two such groups isomorphic to one another?

In this talk we will show that the alternating group of degree 8 is isomorphic to the matrix group $PSL(4,2)$ by considering group actions on a geometry of 7-point planes. No prior knowledge of geometries is required.

1 Motivation

We begin with everyone's favourite mathematical theorem:

Theorem 1 (The Classification Theorem of Finite Simple Groups). *Every finite simple group is isomorphic to one of the following:*

- (i) *A cyclic group of prime order;*
- (ii) *A_n for some $n \geq 5$;*
- (iii) *A simple group of lie type - these include lots of matrix groups such as projective special linear, unitary, symplectic, or orthogonal groups over a finite field; or*
- (iv) *one of 26 sporadic groups.*

The classification theorem has had a profound effect on finite group theory. Indeed, many important theorems have now been proved using it. However, there is repetition within the theorem. Indeed we have the isomorphisms (see [Wil09] for more details).

$$\begin{aligned} PSL_2(4) &\cong PSL_2(5) \cong \text{Alt}(5) \\ PSL_2(7) &\cong PSL_3(2) \\ PSL_2(9) &\cong \text{Alt}(6) \\ PSL_4(2) &\cong \text{Alt}(8) \\ PSU_4(2) &\cong PSp_4(3) \end{aligned}$$

In this talk we will prove the penultimate isomorphism by considering finite geometries.

2 Finite Geometries

We begin with the definition of a geometry.

Definition 2. A geometry over a set Δ is a triple $(\Gamma, *, \tau)$, where;

- Γ is a set (the elements of Γ);
- $*$ is a symmetric relation on Γ (the incident relation of Γ);
- $\tau : \Gamma \rightarrow \Delta$ is a surjective map (the type function of Γ).

such that if $x, y \in \Gamma$ and $x * y$, then $\tau(x) \neq \tau(y)$.

We often talk about the geometry Γ , rather than $(\Gamma, *, \tau)$. Geometries arise in many different areas of mathematics.

Example 3. Consider a cube, having vertex set V , edge set E and face set F . Defining $\Gamma = V \cup E \cup F$, $*$ by

$$a * b \Leftrightarrow a \in b \text{ or } b \in a$$

and $\tau : \Gamma \rightarrow \Delta := \{v, e, f\}$ by

$$\tau x := \begin{cases} v & \text{if } x \in V; \\ e & \text{if } x \in E; \text{ and} \\ f & \text{if } x \in F, \end{cases}$$

then $\Gamma = (\Gamma, *, \tau)$ is a geometry over Δ . •

Example 4. Let G be a finite group, p a prime with $p \mid |G|$. Let Γ be the set of all chains of p -subgroups of G , and suppose the maximal length of such a chain is m (so this is just the order complex of the Brown complex). Define $\Delta := \{1, \dots, m\}$ and define the natural map $\tau : \Gamma \rightarrow \Delta$ by $\tau(x) = \text{length}(x)$. By adding the relation $*$ defined to be inclusion, we have that $\Gamma = (\Gamma, *, \tau)$ is a geometry over Δ . •

Example 4 is a specific case of a simplicial complex, and clearly any simplicial complex of dimension d can be considered as a geometry over $\{1, \dots, d + 1\}$ in the natural way.

We now consider a specific geometry.

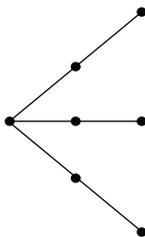
3 7-point planes

Let Ω be a set of seven elements, and denote by \mathcal{L} the set of 3-element subsets of Ω . Our aim is to identify the elements of \mathcal{L} with lines of a projective geometry. Hence we call elements of \mathcal{L} Lines (with a capital !)

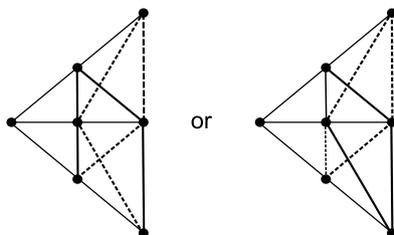
Definition 5. A 7-point plane is a set \mathbb{B} of seven Lines such that any two Lines of \mathbb{B} have exactly one element of Ω in common.

Definition 6. A fan with vertex $\alpha \in \Omega$ is a set of three Lines such that any pair of Lines have only α in common.

We may think of fans diagrammatically as



For each $\alpha \in \Omega$, there are $\binom{6}{2}/6 = 15$ fans on α , and hence there are 105 fans. Moreover, each fan can be extended to a seven point plane in exactly two ways; either



Every 7-point plane contains a fan with vertex α , for each $\alpha \in \Omega$ (as there are $\binom{7}{2} = 21$ common elements of the seven lines in the plane, so 3 pairs of distinct lines each have common element α for a given $\alpha \in \Omega$). It follows that the set \mathcal{A} of 7-point planes on Ω has cardinality 30.

Clearly $Sym(7)$ acts on Ω , and hence permutes the 7-point planes. Since the subgroup of $Sym(7)$ which fixes a 7-point plane is $PSL_3(2)$ (we just assume this) and $[Sym(7) : PSL_3(2)] = 30$, we see¹ that the action of $Sym(7)$ on \mathcal{A} is transitive. Similarly as $PSL_3(2) \subset Alt(7)$ and

¹using the Orbit-Stabilizer Theorem, as $[Sym(7) : Stab(x)] = |Orbit(x)|$ for all $x \in \Omega$.

$[Alt(7) : PSL_3(2)] = 15$, we see that $Alt(7)$ has two orbits on \mathcal{A} , each of length 15.

Let \mathcal{P} and \mathcal{H} denote the two orbits of $Alt(7)$ on \mathcal{A} . we call the elements of \mathcal{P} and \mathcal{H} , Points and Planes respectively. we wish to define a geometry from \mathcal{P}, \mathcal{L} and \mathcal{H} and then prove that these sets are the points, lines and planes of a projective geometry of a vector space of dimension 4 over $GF(2)$.

Set $\Delta := \{P, L, H\}$, $\Gamma = \mathcal{P} \sqcup \mathcal{L} \sqcup \mathcal{H}$ and $\tau : \Gamma \rightarrow \Delta$ in the obvious way:

$$\tau(\sigma) := \begin{cases} P & \text{if } \sigma \in \mathcal{P} \\ L & \text{if } \sigma \in \mathcal{L} \\ H & \text{if } \sigma \in \mathcal{H}. \end{cases}$$

We then define an incidence relation $*$ as follows; a Line $\lambda \in \mathcal{L}$ is incident to a Point or Plane $\mathbb{B} \in \mathcal{P} \cup \mathcal{H}$ whenever $\lambda \in \mathbb{B}$; the Point \mathbb{B}_1 is incident with the Plane \mathbb{B}_2 whenever $\mathbb{B}_1 \cap \mathbb{B}_2$ is a fan. Thus $(\Gamma, *, \tau)$ is a geometry over Δ . To identify the geometry Γ , we proceed to investigate the incident relation $*$ in some detail. First we note that $Alt(7)$ acts transitively on each of the sets \mathcal{P}, \mathcal{L} and \mathcal{H} , and preserves $*$ (*since it merely relabels the elements of Ω*). Moreover, the elements of $Sym(7) \setminus Alt(7)$ interchange \mathcal{P} and \mathcal{H} . We are now in a position to prove our first result:

Lemma 7. (i) *Each Line is incident to 3 Points and 3 Planes.*

(ii) *A Point \mathbb{B}_1 is incident to a Plane \mathbb{B}_2 if and only if \mathbb{B}_1 and \mathbb{B}_2 are incident to a common line.*

Proof. (i) Let λ be a Line, and let $\mathbb{B} \in \mathcal{A}$ contain λ . Each $\alpha \in \lambda$ belongs to two Lines of \mathbb{B} other than λ and these Lines create a partition of $\Omega \setminus \lambda$ into two sets of size 2. Hence we have a bijection between the 3 elements of λ and the 3 partitions of $\Omega \setminus \lambda$ into two sets of size 2. Conversely, every such bijection arises from a unique 7-point plane which contains λ (*to see this just try constructing such a plane*). Since there are 6 such bijections (*since a bijection is from an set of cardinality 3 to another set of cardinality 3, so is an element of $Sym(3)$*), we deduce that λ is contained in six 7-point planes.

Let L denote the stabilizer of λ in $Sym(7)$. Then each element of L permutes the 3 elements of λ , and also permutes the 4 elements of $\Omega \setminus \lambda$. Thus $L = R \times T$, where $R \cong Sym(3)$ and $T \cong Sym(4)$. Since L fixes λ , it acts on the six 7-point planes containing λ . Moreover, the transpositions of L interchange the 7-point planes of \mathcal{P} with those of \mathcal{H} . Thus λ is incident to 3 Points and 3 Planes.

(ii) Clearly the given condition is necessary for \mathbb{B}_1 and \mathbb{B}_2 to be incident. To see that it is also sufficient, assume \mathbb{B}_1 and \mathbb{B}_2 are incident to a common line λ . By (i), there are three Points and three Planes incident to λ . Moreover, every transposition of L fixes a fan containing λ (*possibly*

illustrate this on the board). Each of the 3 transpositions of R maps \mathbb{B}_1 to a Plane containing λ , and there are three such Planes, one of which is \mathbb{B}_2 . Hence B_1 is incident to \mathbb{B}_2 . \square

We now relate this geometry to a certain projective geometry.

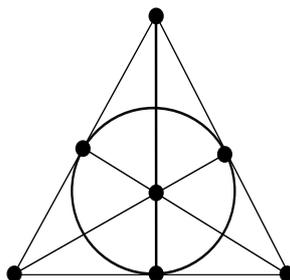
Definition 8. If V is a finite-dimensional vector space, then the set of all subspaces of V , partially ordered by inclusion, is called the projective geometry of V , denoted $\mathcal{P}(V)$.

Theorem 9. The Points \mathcal{P} , Lines \mathcal{L} and Planes \mathcal{H} can be identified with the points (1-dimensional subspace), lines (2-dimensional subspaces) and planes (3-dimensional subspaces) of the projective geometry of a vector space of dimension 4 over $GF(2)$, so that the incidence relation $*$ becomes the usual containment of subspaces.

Proof. If \mathbb{B} is a Point, there are 7 Lines incident to \mathbb{B} . Each of these Lines will be incident to a further two Points. Moreover, any two Points can be incident to at most one common Line (since any two lines of a Point by definition have a common element α , so we can extend these two Lines to a flag at α , and any flag can be extended to a unique Point). Thus we have accounted for all 15 Points. Furthermore, each pair of distinct Points is incident to a unique Line. An analogous argument shows that every pair of Planes are incident to a unique Line. Also, since there are 7 flags in \mathbb{B} and each flag is incident to a unique Plane, there are 7 Planes incident to \mathbb{B} .

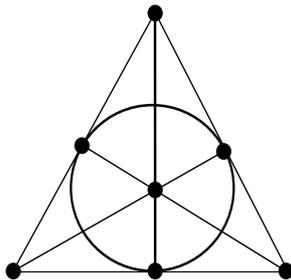
Let $V = \mathcal{P} \cup \{0\}$ and let $\mathbb{B}, \mathbb{B}_1, \mathbb{B}_2 \in \mathcal{P}$ ($\mathbb{B}_1 \neq \mathbb{B}_2$). Define $\mathbb{B} + \mathbb{B} = 0$ and $0 + \mathbb{B} = \mathbb{B} + 0 = \mathbb{B}$, and define $\mathbb{B}_1 + \mathbb{B}_2$ to be the third Point incident to the unique Line determined by \mathbb{B}_1 and \mathbb{B}_2 . Any two Lines with a common Point determine a fan at the common element, and hence are incident to a common Plane, H . This in turn implies associativity of addition, and hence V is a $GF(2)$ -vector space.

To see this, we may note that H is incident to 7 Lines and 7 Points, such that each Line is incident to 3 Points and vice versa. Thus representing Points as dots in the following diagram of the Plane H , we see that



It is then clear that associativity holds. By construction, the sets \mathcal{P}, \mathcal{L} and \mathcal{H} of all Points, Lines and Planes correspond to the 1-, 2- and 3-dimensional subspaces of V , namely the points, lines and planes of the projective geometry of V . \square

It is sometimes useful to represent a 7-point plane, \mathbb{B} , diagrammatically as:



By labeling the elements of Ω as $1, \dots, 7$, we can see that the stabiliser of an incident Point-Line (or Plane-Line) pair has order 24 (since you may permute the elements of the line in any way, and then the Point is uniquely determined by the positioning of one further element of Ω). Since $|Alt(7)|/24 = 105$ and there are $15 \times 7 = 105$ incident Point-Line (Plane-Line) pairs, it follows that $Alt(7)$ acts transitively on such pairs.

Theorem 10. *We have $Alt(7) \subset PGL_4(2)$ and $Alt(7)$ acts 2-transitively on both the points and planes of the projective geometry of dimension 4 (the book says dimension 3) over $GF(2)$.*

Proof. We know that $Alt(7)$ acts transitively on \mathcal{P} , and two distinct elements of $Alt(7)$ have distinct actions on \mathcal{P} . Since the set \mathcal{P} of Points correspond to the points of the projective geometry of dimension 4 over $GF(2)$, it follows that $Alt(7) \subset PGL_4(2)$. Let \mathbb{B}_i (for $i = 1, 2, 3, 4$) be Points, and let λ and λ' be the lines determined by the pairs $(\mathbb{B}_1, \mathbb{B}_2)$ and $(\mathbb{B}_3, \mathbb{B}_4)$. Since $Alt(7)$ acts transitively on Point-Line pairs, there exists $\sigma \in Alt(7)$ such that σ maps (\mathbb{B}_1, λ) to (\mathbb{B}_3, λ') . Moreover, σ maps \mathbb{B}_2 to some Point \mathbb{B}'_4 incident to λ' . The stabilizer in $Alt(7)$ of λ' acts as $Sym(3)$ on the Line λ' . Hence as there are three Points incident to λ' , there exists $\gamma \in Alt(7)$ that maps $(\mathbb{B}_3, \mathbb{B}'_4)$ to $(\mathbb{B}_3, \mathbb{B}_4)$. It follows that $Alt(7)$ acts 2-transitively on \mathcal{P} and hence on the points of the projective geometry. By symmetry, $Alt(7)$ is 2-transitive on \mathcal{H} as well. \square

Corollary 11. $GL_4(2) = SL_4(2) = PSL_4(2) = PGL_4(2) \cong Alt(8)$.

Proof. We know that $[PSL_4(2) : Alt(7)] = 8$ ($|PSL_4(2)| = 20160, |Alt(7)| = 2520$ and $|Sym(8)| = 40320$), and $PSL_4(2)$ acts on the 8 cosets of $Alt(7)$ in $PSL_4(2)$. It follows that we may define a homomorphism $f : PSL_4(2) \rightarrow Sym(8)$. As $PSL_4(2)$ is simple, $\ker f$ is trivial, so we may consider $PSL_4(2) \subset Sym(8)$. As $[PSL_4(2) : Sym(8)] = 2$, and $Alt(8)$ is the only subgroup of $Sym(8)$ of index 2, we must have $SL_4(2) \cong Alt(8)$. \square

References

- [Tay09] Donald E. Taylor. *The Geometry of the Classical Groups*, volume 9 of *Sigma Series in Pure Mathematics*. Heldermann Verlag, Lemgo, Germany, 2009.
- [Wil09] Robert A. Wilson. *The Finite Simple Groups*, volume 251 of *Graduate Texts in Mathematics*. Springer-Verlag, London, United Kingdom, 2009.